

PI	SIGNAL	DIRECTION	LOCATION
PIN AOI	GND	—————————————————————————————————————	
	GND	7	
A03	IRO7		(CZZ)
A04	IRO6		(822)
			(822)
	IROO		
	IR13		(C22) (B22)
A07	IRO8	_	
A08	18/5	<u></u>	(D34) (D34)
A09		<u> </u>	(0347
AIQ	+5V	<u>-</u> _	
AII	+5V	<u> </u>	
A12	SPARE		Z-22\
AI3	ALUOO	<u> </u>	(028)
	ALU02	1	(D28)
A/5	WMBB5		(C37)
A/6		→	(818)
A/7	ØPD04	─	(C24)
	ØP000	-4-	(AZZ)
A19	MADO7	→	(c18)
A20	MADOO	→	(8/8)
A21	GND	-	
	GND	-4-	
	MADOI		(818)
A24		<u></u> — →	(818)
	IRIO	-4-	(CZ2)
	MSELF		(041)
	MADO5		(C18)
A28		 	(C41)
		 - 	(C18)
A29		 	(CIB)
	MAD12	ļ	
	MADIO	ļ	(CIB)
	MADI4		(018)
A 3 3		<u> </u>	ļ
	+5V	<u> </u>	175
	MADI6	- - 	(D18)
	10500	<u></u> →	(C37)
A37		<u></u> →	(DI8)
	RESERVED		
	PAG00	<u>→</u>	(<u>C</u> 31)
A40		>	(831)
A41			
A42			
A43		-0-	(D43)
	SPARE		
A45			1
A46			
A47			1
	B504	 	(848)
A49		'	1
A50			(C43)
	-		1.
A51	SPARE	 	
A52	1	 	
A53		 	
A54		 	
A55		 	
A56		<u> </u>	
A57		<u> </u>	
A58		<u> </u>	(846)
A59		_→	(B46)
A60		- -	(A45)
A6/	B503	→	(648)
A62			(C48)
A63	SPARE	T .	
A64	GND	-0-	
			1
A65	GND	I -	1

PI	SIGNAL	DIRECTION	LOCATION
PIN-801	GND		
B02	GND	—	
	2MHZ	- >	(C43)
	IROI		(C22)
	1RO5	4	(AZZ)
806	IRI4		(C24)
807	IR09	<u> </u>	(C24)
	IRII		(822)
			(034)
			(DJT)
BIO	+51/		
811	+5V		(224)
812	IRI2	<u> </u>	(822)
	STOPI		(C42)
	ALLIOI		(028)
B15	ALU03	<u> </u>	(D28).
816	RESERVED	<u> </u>	L
817	DPD01	──	(822)
818	ØPD05	-	(024)
B19	C.\$01	→	(045)
	IMHZ	→	(C43)
	GND	———	
	GND		
823	RESERVED	 	
			(CI8)
	IDCLI	<u></u> —	(B43)
	ØPD02		(C22)
		 	(A15)
827	SACKI		
<i>B28</i>		<u> </u>	(C43)
<i>B29</i>		-0-	(824)
<i>B30</i>	MADII	<u> </u>	(CIB)
831	MAD13	<u> </u>	(DI8)
<i>B32</i>	MADI5	<u></u>	(DI8)
<i>83</i> 3	+5V	-4	,
<i>B</i> 34	+5V		
835	RESERVED	,	
836	60		(C34)
837	IØ	-4-	(8.48)
	RESERVEL		
839			
	RESERVED	,	
	RESERVED		
			(C37)
	10501	<u>-</u>	(A45)
	P05		1/77/
844	SAARE	 	<u> </u>
<i>B45</i>	SPARE	ļ <u>.</u>	
846+		<u> </u>	
<i>B</i> 47	GND	<u> </u>	
848	PAUSF	<u> </u>	(C45)
B49	RESERVED		<u> </u>
<i>B50</i>	RESERVED		<u> </u>
<i>B51</i>	RESERVED		
B52	P00	-0-	(845)
B53	RESERVED	1	
<i>B</i> 54	RSVP	-0-	(834)
B55	 	-0-	(C37)
856			1,22,2
<u>850</u> 857			
			(844)
<i>858</i>	}		
859			(B34)
860	XCLK	<u> </u>	(C47)
861	20:1HZ	<u> </u>	(C41)
<i>6</i> 62	<u> </u>	<u> </u>	(A45)
			(C46).
£63	 	<u> </u>	(640).
		\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\	(640).

JI	SIGNAL	DIRECTION	LOCATION
PIN OI	ØICLK	(>	(825)
	0102	-0-	(825)
	FW500	->-	(025)
04		-4-	(D47)
05		-	(825)
	1		(AZO)
06		7	(A20)
07			(720)
08	1		(025)
09	1		
10		<u> </u>	(B28)
		 	(B28)
12	ALM	 	(C28)
13	WSTB		(847)
	Ø100		(825)
15	FWUL		(B45)
16	LNKOZ		(838)
/7	WR501		(C25)
18	FREU		(828)
19	INKOI		(037)
20	MRS00		(C25)
# 21	MRS01	1	(C25)
22	C508	->-	(D41)
23		_ <u>_</u>	
24	-	-4-	(B35)
25		-	(A37)
			(838)
26		 	(C25)
27			
	SIF	 -	(C28)
29		 	(828)
30		├	(037)
31			(037)
32			(037)
33	LNKOO		(025)
34	MSEL		(C28)
35		<u> </u>	(025)
36	MWMXN	<u> </u>	(034)
37	T5TR		(A21)
38	IPCLR	_>	(841)
39	PCSOO	—>>—	<i>(B37)</i>
40		->-	(C37)
4/	RMXON	-4-	(A22)
42		>	- (837)
43		->-	(C46)
44		_ \	(837)
43		-4-	(022)
		-X	(C28)
46		-	(C28) (A44)
47		<u> </u>	(B29)
48		-0-	
49		-	(848)
50	GND	<u> </u>	

J2	DIGNAL	DIRECTION	LUCATION
PIN OI	PØMO4	→> —	(A34)
02	RØMO6		(835)
03	ROMOZ		(C34)
04	ROMOI	+	(C34)
	RMA02	—>—	(837)
	SPARE		
	SPARE		
08	SPARE	-	İ
09			(838)
10	RØM07	─	(835)
11	SPARE		
12	SPARE		
13	SPARE		
14	RAEN	 D	(831)
15	SPARE	<u> </u>	
16	1		
17	1		
	SPARE		
A	RØM05		(834)
	TROM2	<u> </u>	(B34)
C	RØM03	<u> </u>	(C34)
D	SPARE		
E	RMA00	>	(A37)
F	SPARE		l
H	SPARE		
J	SPARE		×
K	TRØM3		(B34)
۷	C504 ·	→	(042)
М	SPARE		
N	SPARE		
Ρ	SPARE		
·R	CARRY	→	(842)
. \$	SHØRT	>	(835)
<u> </u>	STOPF	>	(C41)
U	SPARE		
V	SPARE		L

	Į	REV	DESCRIPTION			DR	СĦ	DATE	APPROVAL
						•	•	•	
							•		
					0.50				
			RPI		RP2				
			WMBBS 2		1 +5V 19 IØ	_			
	((c38)	ALUO3 10			C38	ソー		
	(029)	ALUOZ 9		12 TAPET		,		*
		029)	1/1/0/ 8						
		(029)	ALU007		ACINEN	C47))		
		(D35)	IL6 5		DOCTO	(C48 (C42,	·/		
		035)	<i>1</i> 67 4		10 14000	(C3			
		035)	<i>18/5</i> 3		710300	(038	š)		
3 2	9 (24 (4)	3,A44)	+5R2 6		10 30	C35			
	,		RP3 +5V		RP 5		-		
		۱ مسد ۱	Øv00 7				~ 1		
		B25)	UNKOI 5		1	102	<i>9)</i> 0)		
	(038	N/C 6		3 WRSO/	(04)	7/ -)		
	/	025)	FWSO1 2		7 FREU	(028		•	
	((D38)	TTM003		2 N/C		"		
		(<i>82</i> 5)	Ø1018		6MRSOO	(CZ	5)		
		(025)	FW5004	•	SMASOI	(C25	5)		
		(825)	Ø102 9		O PKEL	(BZ	8)		
		(825)	ØVCLK 10 RP4		RP6	(CZ	5)		
			+5V 1		1 +5V				
		(029)	ALM 3		4 MWMXN	COR	5)		
į	- 1	(c29)	SIF 5		9 PCSOO	(B3)	g)		
		(C28)	ALCH 4		9 PCSOO 10PCSO3 8 PCSO1				,
		(838)	TNKOSZ		BPCSOI .	838	()		
	*	(038)	TTMO/ 10						
		(038)	TTM02 8		2 ROM 00	C35			
	((025)	MSEL 7		3 RMADI	538,)		
		(C28)			6 N/C				
		(025)	RP7		RP8				,
	•		+5V 1		1 +5V				
1		(838)	RMAOZ 2		9 TROMT 10TROMS	837)		
		(838)			1700M07		,		I
		(c35)	ROMO2 5		2+5R1	83	5)		. •
		(035)	ACM036		2+5R1 4 N/C	C+9.	543,	44/)	
		(C35)	TROM2 8 R2M067		6 NIC	,			
		(834)	R2M067		E DACH	(B4.			1
		(B35)	ROMOS 10 ROMOS 9		0 11/6	(B31		244 ^	43)
		(835) (A35)	ROMO19		2 SULLOT			,B44,C	73/
	(~ 22)				83.	رد		1
1									

REVISIONS

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ALLRESISTOR PACKS ARE IK, ±5%, 1/8W

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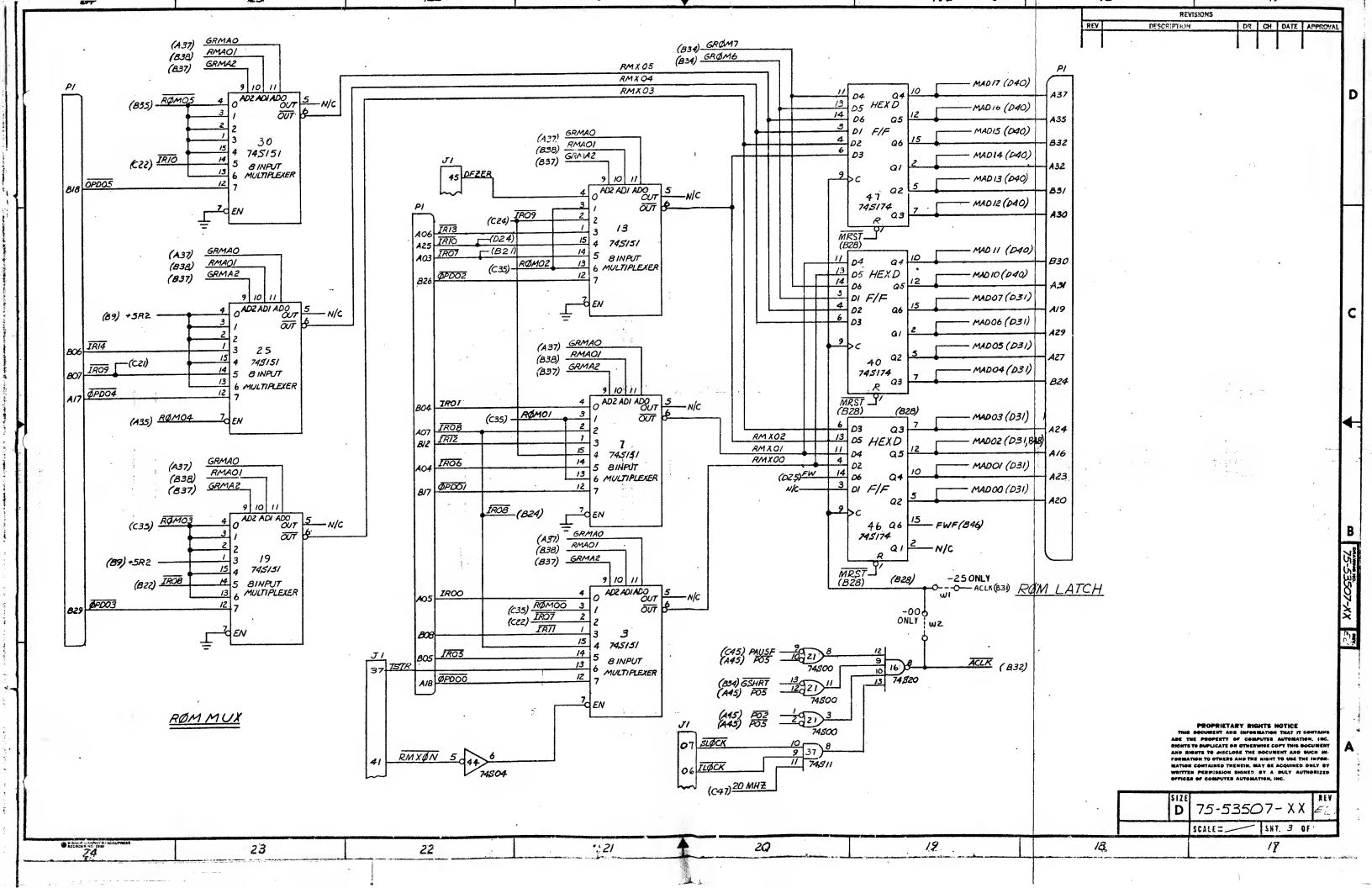
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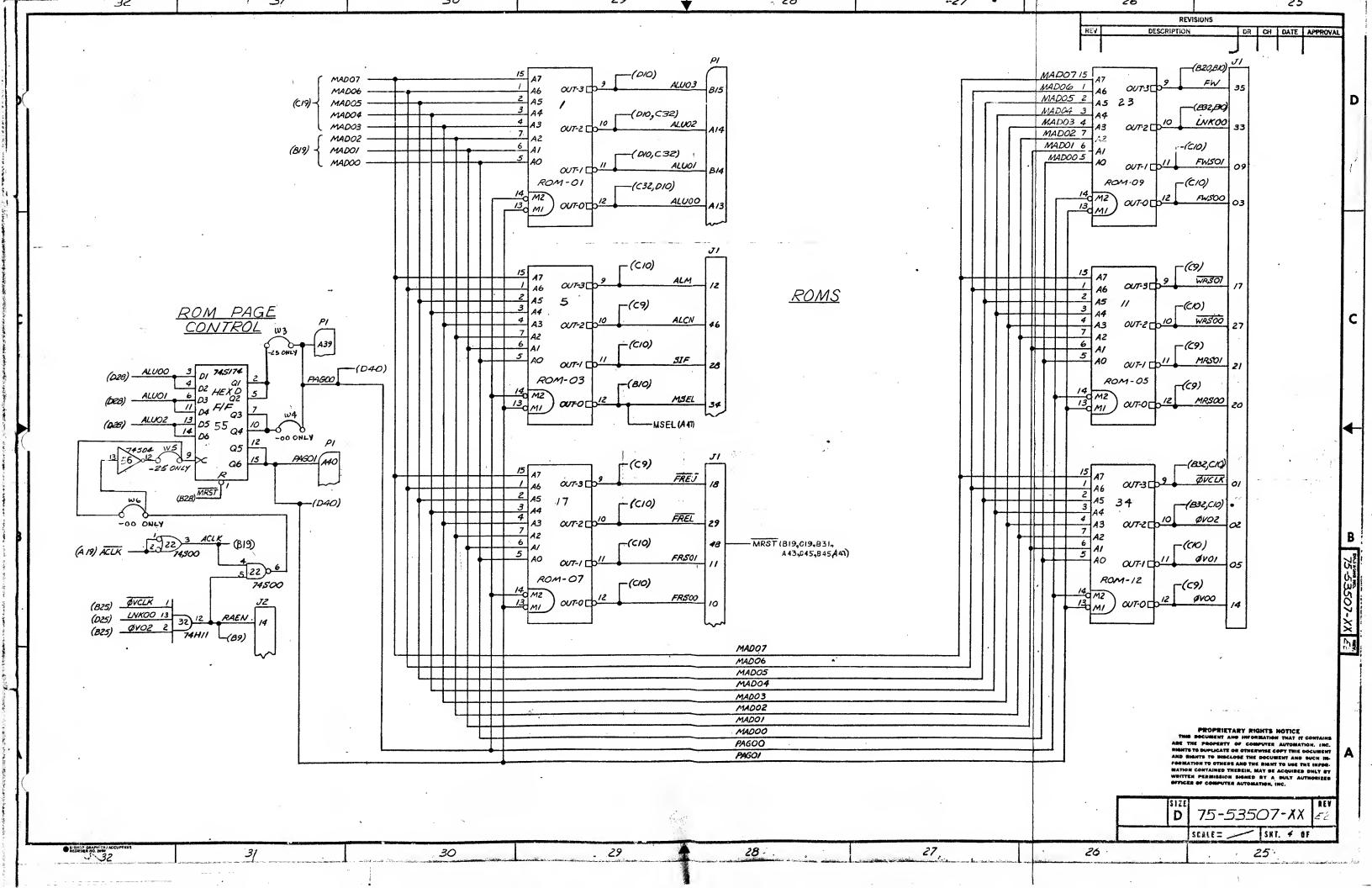
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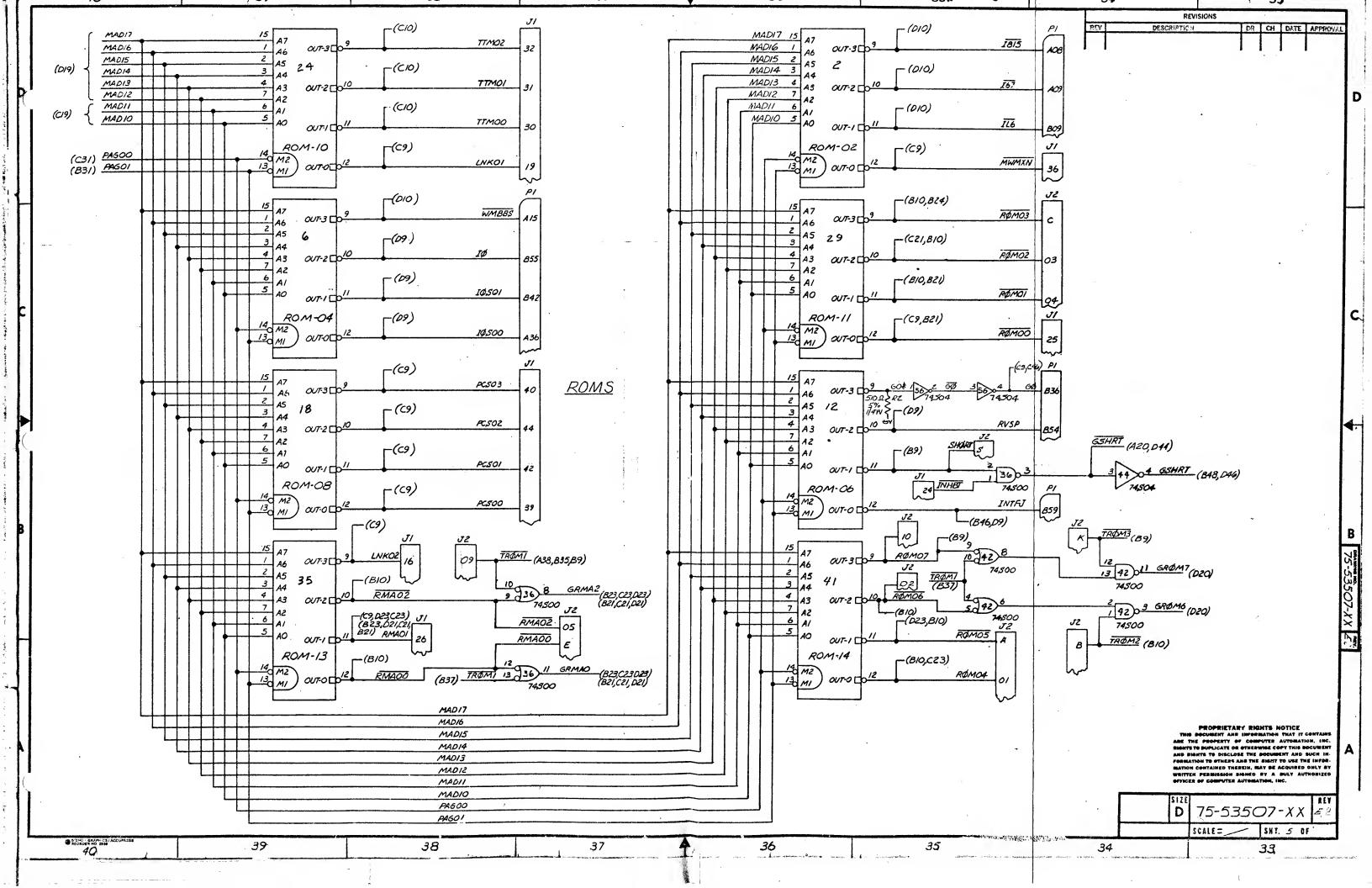
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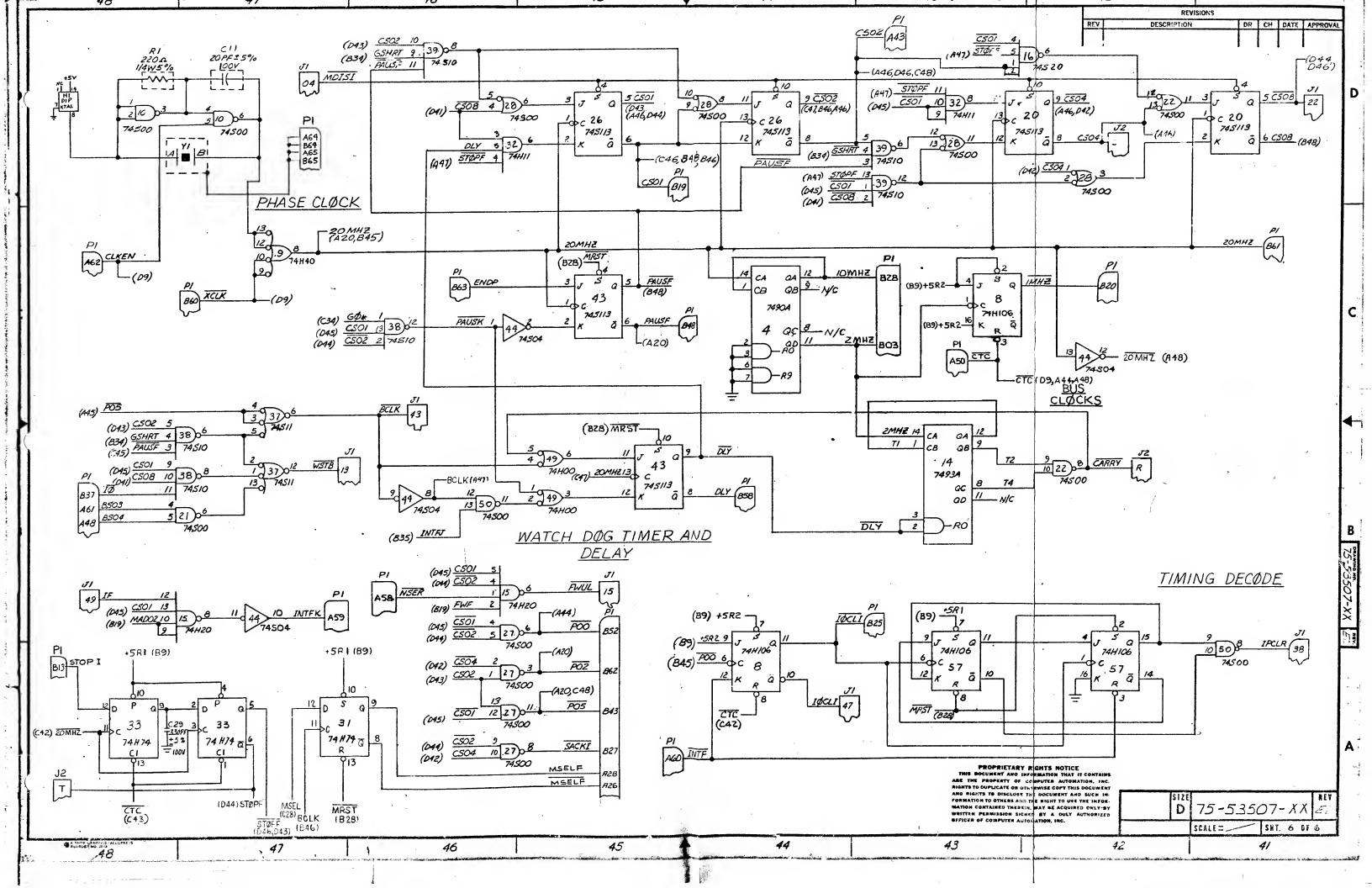
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ComputerAutomation® ENGINEERING 1865¹ Von Karman, Irvine, Calif. NOTICE					NO. 191819	13 111	
1865¹ Vo	on Karm	an, Irvir	ne, Calif.		<u> </u>		1-1-1-1
DOCUMENT NO.	<u> </u>	EV.	TITLE		INCORP.	TYPE	
	iS	WAS		····	DATE	AEN	O
75-53507-XX	E4	E3	LOGICILSI PR HALF CARD.	20cessor		STOP ORDER	
		 			1	DEVIATION	. 🗖
74-53507-00	E4	E3	DETAIL			RELEASE STANDARD	***
73-53507-XX	E4	E3	A56Y		e de	CLASS	1
70 - 53507-00	E4	E3	В/М		7 1 63	A-MAND/FUNC	
					7 1 83	B-NON-MAND/FUN	
70 - 53507-25	E4	E3	B/M		Jrn.	C-RECORD CHG	
						AFFECTED	
						HARDWARE CHG.	PRIM. SEC.
		-			· · · · · · · · · · · · · · · · · · ·	SOFTWARE CHG.	
						PUBL. CHG.	
EFFECTIVITY NOTES	S :					CAPABLE CHG.	
						DOC. CHG. CONFIGURATIONS	
						PROCEDURES	
REASON FOR CHAN	GE:			REA NO.	1102	TOOLING	
JUMPER SPE	LIFIC	ATIO	ONS ARE	CO-ORD W		TEST EQUIP.	
INCORRECT	.,			CO-ORD W	* * *	EFFECTIV	
DIGCO CADO!					11 11 2	ACTIVITY	URSP
						NOTIFY VEND IN STOCK	
· ·			•		1	KITTING	
						ASSEMBLY	
<i>'</i>			•			TOUCH UP	
					*	IPT	
					•	FIN GOODS CUST. RET.	-
					**	REWK TEST I	PEO'D
					· ·	CONTINUITY	
				,	*	CABLE SCAN	
DESCRIPTION OF CH	IANGE	:			•	CAPABLE	
A REWORK				•		MEMORY	
I. REMOVE		MDE	26		` '	CARD	. 0
1						FINAL NO TEST REQ'D	
. 75-5350		_	W4			APPROVA	10
75-5350	7-29	7	W3			ENGR. Bayes	
2. APP UL	IMPE	26			:	SOFTWARE	
75-5350			143			Q.A.	Branin 1
75-5350							Man M
i i			•				<u> </u>
NOTE: J	UMPI	er5	1,2,5 AND 6	NOT AF	166761.)	MATERIALS (TEST ENGR.	25 mont
						TECH SERV	(20)
						CUST SERV ;	Hal Terre
						MFG. ENGR	
						PUBLICATIONS	
				•		DR. BY: P. PARKE	
						CHKD. BY:	X70112041
,	•					DATE: X M	22
							HEET OF 3

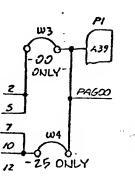
A. 70-53507-00,25 B/M'S 1. CHANGE REF PESIG OF ITEM 26

15: -00 W2,W3,W6 -25 W1,W4,W5

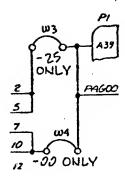
<u>WAS:</u> -00 WZ, W4, W6 -25 WI, W3, W5

B. 75-53507-XX LOGICS
1. ADD JUMPERS W4, W3

15:



WAS:





C. 75-53507-XX

1. CHANGE TABULATION BLOCK JUMPERS

15:

COMPONENT SIDE

	TABULATION	BLØCK ·	
DASH NO.	DESCRIPTION	BILL OF MATERALS	JUMPER
-00	BASIC	70-53507-01	WZ,W3,W6
-25	LS12/60 ROM	70-53507-25	WI.W4.W5

WAS:

COMPONENT SIDE

	TABULATION	BLOCK	
DASH NO.	DESCRIPTION	BILL OF MATERIES	JUMPER
-00	BASIC	70-53507-01	WZ,W4,W6
-25	LS12/60 ROM	70-53507-25	MI,W3,W5

(CM	ComputerAutomation ®
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				•
SHEET	3	OF	3	